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**APPLICATION ELEMENTS**

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2. ☒ Specification [Total Pages  ]  
(preferred arrangement set forth below)
  - Descriptive title of the Invention
  - Cross References to Related Applications
  - Statement Regarding Fed sponsored R & D
  - Reference to Microfiche Appendix
  - Background of the Invention
  - Brief Summary of the Invention
  - Brief Description of the Drawings (if filed)
  - Detailed Description
  - Claim(s)
  - Abstract of the Disclosure
3. ☒ Drawing(s) (35 USC 113) [Total Sheets  ]
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  - a. ☐ Newly executed (original or copy)
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8. ☐ Assignment Papers (cover sheet & document(s)) to TOKYO  
ELECTRON LIMITED OF JAPAN WILL FOLLOW
9. ☐ 37 CFR 3.73(b) Statement ☐ Power of Attorney  
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10. ☐ English Translation Document (if applicable)
11. ☐ Information Disclosure Statement (IDS)/PTO-1449 ☐ Copies of IDS Citations
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Status still proper and desired
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(if foreign priority is claimed) of  
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**18. CORRESPONDENCE ADDRESS**

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- ☒ If a paper is untimely filed in the above-referenced application by applicant or his/her representative, the Assistant Commissioner is hereby petitioned under 37 C.F.R. § 1.136(a) for the minimum extension of time required to make said paper timely. In the event a petition for extension of time is made under the provisions of this paragraph, the Assistant Commissioner is hereby requested to charge any fee required under 37 C.F.R. § 1.17(a)-(d) to **Deposit Account No. 03-1952**. However, the Assistant Commissioner is **NOT** authorized to charge the cost of the issue fee to the Deposit Account.

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Dated: July 7, 2000

Respectfully submitted,

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35           A wafer counter is disposed above the unloading stage. The  
wafer counter counts the number of the wafers contained in each  
carrier and inspects the carrier for jump-slots before the wafers

are taken out of the carrier. A wafer counter is disposed above the loading stage to count the wafers after the wafers have been loaded into the carriers so that any wafers may not be left in the cleaning and drying unit.

5 In the conventional carrier receiving unit and carrier delivery unit, the lifters and lifter driving mechanisms are disposed in spaces above the receiving stage and the delivery stage, respectively. Therefore, it is possible that the operator touches the lifter or the driving mechanism accidentally when carrying the  
10 carriers onto the receiving stage or taking out the carriers from the delivery stage and the operator is injured. Moreover, the carrier receiving unit and the carrier delivery unit are congested with the lifters and the driving mechanism and have a complicated configuration. Since the wafer counters are disposed above the  
15 unloading stage and the loading stage, respectively, it is possible that accidents occur during inspection, and the carrier receiving unit and the carrier delivery unit are further congested with the wafer counters.

## 20 SUMMARY OF THE INVENTION

Accordingly, it is a first object of the present invention to provide a container handling system in which carrier moving means are not disposed in spaces above stages on which carriers are placed.

25 A second object of the present invention is to provide a container handling system having inspecting means not disposed in spaces above stages and capable of efficiently inspecting the storage condition of substrates contained in containers.

A third object of the present invention is to improve container handling efficiency.

30 A first aspect of the present invention is a substrate processing apparatus comprising: a plurality of stages, on each of which a container for containing substrates therein is to be placed; and a first section at which the substrates are taken out from the container and/or are put into the container, wherein a first stage  
35 amongst the stages is provided at the first section; and a movable table carrying the container between the first stage and one of the stages other than the first stage, while the container being placed

thereon.

5 A second aspect of the present invention is a method of carrying a container for containing substrates between two stages included in a substrate processing apparatus, said method comprising the steps of: (a) moving a movable table for transporting a container to a position below a surface of a first stage on which a container is placed thereon; (b) raising the movable table through a cut-away area formed in the first stage to a position above the surface of the first stage, thereby lifting up the container from the first stage by the movable table; (c) withdrawing the movable table, on which the container is placed, from a position above the first stage; (d) moving the movable table to a position above a second stage; and (e) lowering the movable table through a cut-away area formed in the second stage to a position below a surface of the second stage, thereby placing the container on the second stage.

10 A third aspect of the present invention is a method of handling containers for containing substrates, said method comprising the steps of: (a) delivering a plurality of containers containing substrates onto a receiving stage; (b) transferring one of the plurality of containers to an unloading stage; (c) taking out substrates from the container transferred to the unloading stage; and (d) repeating the steps (b) and (c).

15 A fourth aspect of the present invention is a method of handling containers for containing substrates, said method comprising the steps of: (a) putting substrates into a container on a loading stage; (b) transferring the container containing the substrates to a delivery stage after the completion of the step (a) before putting substrates into another container; (c) repeating the steps (a) and (b), thereby collecting a plurality of containers containing substrates on the delivery stage; and (d) delivering the plurality of containers collected on the delivery stage after the completion of the step (c).

20 A fifth aspect of the present invention is a method of handling containers for containing substrates, said method comprising the steps of: (a) delivering a plurality of containers each containing substrates onto a receiving stage; (b) transferring one of the plurality of containers to a loading/unloading stage; (c) taking

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### BRIEF DESCRIPTION OF THE DRAWINGS

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1;

the cleaning apparatus shown in Fig. 1:

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Fig. 5 is a sectional view taken on line A-A in Fig. 3;

Fig. 6 is a perspective view of a moving mechanism;

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carrier;

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predetermined number of wafers;

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less than a predetermined number of wafers;

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The receiving/delivering department 2 has a receiving section 2A, a delivery section 2B and a loading/unloading section 2C. The receiving section 2A receives wafers W to be cleaned by the cleaning apparatus 1 from an external of this cleaning apparatus. The delivery section 2B delivers wafers W processed by the processing department

4 from the cleaning apparatus 1. In the loading/unloading section 2C, wafers W to be subjected to cleaning and drying are taken out from carriers C, and cleaned and dried wafers W are put in carriers C.

5 In the carrier storage department 3, a storage device 5 for storing carriers C in a vertical direction, a lifting mechanism 6 for lifting carriers C, and a storage device 7 are aligned. The lifting mechanism 6 is capable of receiving and lifting carriers C transferred by a movable table 23 (described in detail hereinafter) and then of putting carriers C on empty shelves of the storage devices 10 5, 7. The lifting mechanism 6 is also capable of taking carriers C out of the shelves and carrying carriers C to the moving table 23.

The storage devices 5, 7 may have lifting means for lifting 15 carriers C so that the carriers can be transferred between the storage devices 5, 7 and the lifting mechanism 6.

The processing department 4 has a drying device 9, a cleaning and rinsing device 10, a wafer holder cleaning and drying device 11 and a cleaning and rinsing device 12 arranged in that order from 20 the side near the carrier receiving/delivering department 2. The drying device 9 dries wafers W by using isopropyl alcohol vapor (IPA vapor). The cleaning and rinsing device 10 cleans wafers W with a cleaning liquid containing a chemical liquid as a principal component and rises the wafers W with pure water. The wafer holder cleaning and drying device 11 cleans and dries wafer holding members 8a and 25 8b included in a carrying device 8. The cleaning and rinsing device 12 cleans wafers W with a cleaning liquid containing a chemical liquid different from that contained in the cleaning liquid used by the cleaning and rinsing device 10 and rinses the wafers with pure water.

30 The cleaning and drying department 4 is provided with the carrying device 8 for carrying wafers W to and from the devices 9 to 12. The carrying device 8 has the pair of holding members 8a and 8b capable of being moved toward and away from each other and of moving in the directions of the arrows Y (Fig. 2).

35 As shown in Fig. 3, a carrier handling system 20 in a preferred embodiment according to the present invention is installed in the carrier receiving/delivering department 2. The carrier handling

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system 20 includes a receiving stage 21 installed in the receiving section 2A, a delivery stage 22 installed in the delivery section 2B, a loading/unloading stage 23 installed in the loading/unloading section 2C, the movable table 24 for carrying carriers C from and to the stages 21, 22 and 23. The stages 21, 22 and the stage 23 are spaced by a path 25 in which the movable table 24 moves.

Preferably, the stages 21 and 22 are on the same level. More preferably, stages 21, 22 and 23 are on the same level.

The receiving section 2A is demarcated by side walls 26 and 27 disposed on the opposite sides thereof, and the delivery section 2B is demarcated by the side wall 27 and a side wall 28 disposed on the opposite sides thereof. The receiving stage 21 is secured to the side walls 26 and 27, and the delivery stage 22 is secured to the side walls 27 and 28.

The receiving stage 21 is a plate-shaped member having an upper surface on which carriers C are placed. Two carriers C can be placed on the receiving stage 21. Note that a predetermined position on the stage at which a carrier C is placed will be referred to as the term "station". Cut-away areas 30 and 31 are formed in portions of the receiving stage corresponding to the stations 21A and 21B. Each of the cut-away areas 30 and 31 extends from an end of the receiving stage 21 on the side of the path 25 to a position slightly beyond the corresponding stations 21A and 21B. The delivery stage 22 is the same in construction as the receiving stage 21. Stations 22A and 22B are set on the delivery stage 22. The delivery stage 22 is provided with cut-away areas 32 and 33 of the same shape as that of the cut-away areas 30 and 31 in portions thereof corresponding to the stations 22A and 22B. A single station 23A is set on the loading/unloading stage 23. The loading/unloading stage 23 is provided with a cut-away area 76 of the same shape as that of the cut-away areas 30 and 31 in portion thereof corresponding to the station 23A.

The loading/unloading stage 23 may be formed with an increased area allowing, for example, two carriers C to be placed thereon, and may be provided with stations and cut-away areas corresponding to the number of carriers to be placed thereon.

Each of the cut-away areas of the stages is formed in a shape

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and dimensions that allow the movable table 24 to move vertically through the cut-away area and prevent a carrier C placed at the corresponding station of the stage from falling through the cut-away area from the stage (see Figs. 3 and 7).

Fig. 5 is a sectional view taken on line A-A in Fig. 3. As shown in Fig. 5, a table moving mechanism 40 for moving the movable table 24 is disposed on a level lower than that of any one of the receiving stage 21, the delivery stage 22 and the loading/unloading stage 23.

10           The table moving mechanism 40 will be described with reference to Fig. 6. A shaft 45 is joined to the lower surface of the movable table 24. The shaft 45 can be moved vertically by a lifting mechanism 46, such as a cylinder actuator, to move the movable table 24 vertically, i.e., in the directions of the arrows Z in Fig. 6.

15           The lifting mechanism 46 is attached to a sliding member 48 combined with a horizontal guide rail 47 and is capable of horizontally moving along the length of the guide rail 47 in the directions of the arrows R in Fig. 6. The sliding member 48 is provided with a driving mechanism 48A (illustration of particulars of the driving mechanism 48A is omitted) for moving the sliding member 48  
20 along the guide rail 47. The guide rail 47 has a base end part fixed to the upper surface of a base plate 49. The base plate 49 is supported on a shaft 51. The shaft 51 can be turned by a turning mechanism 50, such as an electric motor. Thus, the guide rail 47 can be turned  
25 in a horizontal plane in the directions of the arrows  $\theta$  in Fig. 6 by the turning mechanism 50. A base 52 serving also as a guide rail is extended along the length of the path 25. The turning mechanism 50 is supported on the base 52 for horizontal sliding movement in the directions of the arrow Y in Figs, 2 and 6. The turning mechanism  
30 50 is provided with a driving mechanism 50A for moving the turning mechanism 50 along the base 52.

The movable table 24 employed in this embodiment has a shape substantially resembling the letter H. As shown in Fig. 6, the movable table 24 has projecting parts 24a at its four corners, and the projecting parts 24a are provided with grooves 55 for receiving lugs projecting from peripheral parts of the lower surface of a carrier C, respectively. The movable table 24 is provided with a wafer counter

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23.

Each of carriers C to be handled by the handling system 20 is provided with a plurality of slots and is capable of containing, for example, twenty-five wafers W in an upright position in a parallel arrangement. The carrier C has a lower wall provided with an opening. Generally, the wafer W is circular and is provided with a notch Wa in its circumference. An alignment device, not shown, disposed in the carrier receiving/delivering department 2 uses notches Wa formed in the circumferences of wafers W to align the wafers W in the carrier

C.

A series of processes to be carried out by the cleaning apparatus 1 will be described hereinafter.

The front shutter 65 of the receiving section 2A is opened and the back shutter 67 of the same is closed. When operating the back shutter 67, the movable table 24 and the guide rail 47 are held at positions indicated by two-dot chain lines 24' and 47' in Fig. 3 to avoid obstructing the movement of the back shutter 67.

As shown in Fig. 4, an operator or an AGV carries two carriers C each containing, for example, twenty-five wafers W to be cleaned to the receiving section 2A of the cleaning apparatus 1. After the carriers C have been placed at the stations 21A and 21B of the receiving stage 21 as shown in Fig. 5, the front shutter 65 is closed and the back shutter 67 is opened.

Subsequently, the movable table 24 and the guide rail 47 are turned from positions indicated by two-dot chain lines in Fig. 3 to positions indicated by solid lines 24 and 47 in Fig. 3 to extend the guide rail 47 on a level below the station 21A of the receiving stage 21. Then, the movable table 24 is advanced to a position indicated by two-dot chain lines 24' in Fig. 7. While the movable table 24 is thus advanced, the wafer counter 60 counts the wafers W and inspects the carrier C for jump slots.

Such operations of the movable table 24 and the wafer counter 60 will be described with reference to Figs. 8 to 11. The movable table 24 is advanced from a level slightly lower than that of the movable table 24 shown in Fig. 8 to a position shown in Fig. 8. Subsequently, the movable table 24 is raised slightly to insert the light projector 61 and the light receiver 62 into the carrier C as

shown in Fig. 12. Then, the movable table 24 is advanced on the level shown in Fig. 8 to and stopped at a position shown in Fig. 9. While the movable table 24 is advanced from the position shown in Fig. 8 to the position shown in Fig. 9, the light projector 61 and the  
5 light receiver 62 scan the interior of the carrier C.

A light beam projected by the light projector 61 is intercepted by the wafers W. The light receiver 62 provides a pulse every time the light beam is intercepted. Therefore when the wafers W are received normally in slots 75 as shown in Fig. 13A, the light receiver  
10 62 generates a regular pulse signal as shown in Fig. 13B. The number of the wafers W is known by counting the pulses of the pulse signal.

When there is a vacant slot 75 in the carrier C as shown in Fig. 14A, the light receiver 62 does not generate any pulse at a position corresponding to the vacant slot 75 as shown in Fig. 14B.  
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When there is a jump slot in the carrier C as shown in Fig. 15A, the light receiver 62 generates an abnormal pulse having a pulse width greater than that of normal pulses at a position corresponding to the jump slot as shown in Fig. 15B. Thus, it is known that the carrier C has a jump slot or jump slots from the abnormal pulse signal  
20 as shown in Fig. 15B.

After it has been confirmed that a predetermined number of wafers W are contained correctly in the carrier C, the movable table 24 carries the carrier C to the loading/unloading stage 23. If any abnormality, such as a shortage of wafers, is found in the carrier  
25 C, the carrier C is taken out of the receiving stage 21 and another carrier C expected to contain wafers W normally is supplied to the receiving stage 21. Since the number and condition of the wafers W in the carrier C are inspected during a preparatory operation before lifting up the carrier C, the throughput of the cleaning process  
30 can be enhanced. Since the number and condition of the wafers W in the carrier C are inspected upon the placement of the carrier C on the receiving stage 21, problems can be found measures can be taken at an early stage of the cleaning process.

To carry the carrier C from the receiving stage 21 to the  
35 loading/unloading stage 23, the movable table 24 is raised to lift up the carrier C from the receiving stage 21 as shown in Fig. 10. Then, the movable table 24 is retracted toward the path 25 to shift

the carrier C away from a position above the receiving stage 21 as shown in Fig. 11. When the movable table 24 is thus retracted, the shaft 45 moves through the cut-away area 30. Then, as shown in Fig. 16, the turning mechanism 50 turns the movable table 24 and the guide rail 47 counterclockwise through an angle of  $90^\circ$  in a horizontal plane.

Then, the driving mechanism 50A drives the turning mechanism 50 for movement along the base 52 without changing the direction of the guide rail 47 to move the movable table 24 horizontally so as to carry the carrier C to a position indicated by two-dot chain lines in Fig. 16. Subsequently, the turning mechanism 50 turns the guide rail 47 counterclockwise, as viewed in Fig. 16, through an angle of  $90^\circ$  in a horizontal plane to locate the guide rail 47 under the loading/unloading stage 23. Then, the movable table 24 is moved horizontally along the guide rail 47 to locate the carrier C above the loading/unloading stage 23. Then, the lifting mechanism 46 lowers the movable table 24 to a level below the loading/unloading stage 23 to transfer the carrier C from the movable table 24 to the loading/unloading stage 23. Then, the movable table 24 is retracted from a position below the loading/unloading stage 23 along the guide rail 47.

Upon the placement of the carrier C containing the wafers C on the loading/unloading stage 23, the wafer holder 80 is railed as shown in Fig. 17. Consequently, the wafer holder 80 enters the carrier C through the opening formed in the bottom wall of the carrier C, receives the wafers W held in the slots of the carrier C in its grooves 81 and takes out the wafers W from the carrier C. The wafer holder 80 is raised to a position indicated by two-dot chain lines in Fig. 17. Then, the wafer holder 80 is turned through an angle of  $90^\circ$  about a Z-axis. Then, the holding members 8a and 8b of the carrying device 8 take up the wafers W from the wafer support hand 80 and carries the same to the processing department 4.

The wafers W are carried to the cleaning and rinsing devices 10 and 12 successively for cleaning, and are carried to the drying device 9 for cleaning. The wafers W thus cleaned and dried are returned to the loading/unloading stage 23. The foregoing operations for taking out the wafers W from the carrier C are reversed to return

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the wafers W thus processed by the processing department 4 into the carrier C kept on the loading/unloading stage 23.

Then, the carrier C placed on the loading/unloading stage 23 is supported on the movable table 24 by operations similar to those previously described with reference to Figs. 8 to 11. The wafer counter 60 inspects the number and condition of the wafers W contained in the carrier C while the movable table 24 is being moved to a position directly below the station 23A to confirm that any wafers W are not left in the processing department 4.

Then, movable table 24 transfers the carrier C from the loading/unloading stage 23 to the delivery stage 22. The carrier C is placed on the delivery stage 22 at the station 22A. During this operation, the back shutter 71 of the delivery section 2B is open and the front shutter 70 of the same is closed.

Subsequently, the other carrier C set on the receiving stage 21 at the station 21B is carried to the loading/unloading stage 23, wafers W are taken out of the carrier C and are subjected to the cleaning and drying processes. Then, the foregoing operations are repeated to carry the carrier C containing the processed wafers W from the loading/unloading stage 23 to the delivery stage 22. This carrier C is placed on the delivery stage 22 at the station 22B.

Subsequently, the movable table 24 and the guide rail 47 are moved away from under the delivery stage 22, the back shutter 71 of the delivery section 2B is closed and the front shutter 70 is opened. Then, the operator takes out the two carriers C from the delivery section 2B through the front opening 37.

As mentioned above, two carriers C are carried to the receiving stage 21, the two carriers C are carried one at a time from the receiving stage 21 to the loading/unloading stage 23. Every time one carrier C is placed on the loading/unloading stage 23, wafers W are taken out of the carrier C and are subjected to a predetermined cleaning process. Then, the processed wafers W are put in the carrier C on the loading/unloading stage 23 and the carrier C is carried horizontally from the loading/unloading stage 23 to the delivery stage 22. After the two carriers C have been placed on the delivery stage 22, the two carriers C are delivered from the delivery section 2B. When delivering the carriers C from the delivery section 2B,

the front shutter 70 is opened and the back shutter 71 is closed. The interlocked operations of the shutters 35 and 37 and those of the shutters 70 and 71, and the operations of the moving mechanism 40 are controlled by a controller, not shown.

5       The carrier handling system 20 according to the present invention has the following advantageous effects.

      Since the carrier C is placed on and carried by the movable table 24, a space 42 extending over the receiving stage 21, the delivery stage 22 and the loading/unloading stage 23 is always  
10       vacant.

      Since the table moving mechanism 40 is disposed on a level lower than that of any one of the receiving stage 21, the delivery stage 22 and the loading/unloading stage 23, any components of the driving mechanism of the table moving mechanism 40 do not enter the  
15       space 42 extending over the stages 21, 22 and 23 when carrying the carrier C. As known from the foregoing description, only components that have a chance to enter the space 42 extending over the stages 21, 22 and 23 are only the movable table 24, the shaft 45 and the wafer counter 60. Accordingly, injuries to the operator due to the  
20       accidental contact of the operator with the movable table 24 or the moving mechanism 40 can be prevented and safety can be secured. Since the space 42 extending over the stages 21, 22 and 23 is always vacant, the carrier handling system 20 is simplified. Part of the vacant space 42 may be effectively used, for example, as a storage space  
25       for storing carriers C provided that operations for moving the carrier C are not obstructed.

      Since it is a rule to close either the front or the back shutter of the receiving section 2A and either the front or the back shutter of the delivery section 2B, injuries to the operator due to accidental  
30       contact between the operator and the moving component of the carrier handling system 20 can be avoided with reliability.

      Since the wafer counter 60 is inserted into the carrier C through the opening formed in the bottom wall of the wafer W to inspect the wafers W contained in the carrier C, the wafer counter 60 is  
35       rarely exposed during inspection and hence accidental contact between the wafer counter 60 and the operator can be avoided. Since the wafer counter 60 is incorporated into the movable table 24, the

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carrier handling system 20 is simplified.

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A cleaning apparatus 100 shown in Fig. 18 in a modification of the cleaning apparatus 1 shown in Fig. 1 may be provided with a single receiving/delivering section 2D as shown in Fig. 18 instead of the receiving section 2A and the delivery section 2B shown in Fig. 3. The cleaning apparatus 100 shown in Fig. 18 is provided with a single receiving/delivering stage 101 having stations 102 and 103, and provided with openings at positions corresponding to the stations 102 and 103. The receiving/delivering section 2D has a front opening 104 and a back opening 106. The front opening 104 can be covered with a front shutter 105 that is raised to a closing position. The back opening 106 can be covered with a back shutter, not shown, that is lowered to a closing position. The cleaning apparatus 100 is the same in other respects as the cleaning apparatus 1 shown in Fig. 3.

The operation of the cleaning apparatus 100 shown in Fig. 18 will be described hereinafter. Two carriers C are carried to the receiving/delivering section 2D and are set at the stations 102 and 103 on the receiving/delivering stage 101. The carrier C at the station 102 is moved by the movable table 24 to the loading/unloading stage 23, wafers W are taken out of the carrier C and the wafers W are carried to the processing department 4. The empty carrier C is kept on the loading/unloading stage 23. After being processed, the wafers W are returned to the carrier C kept on the loading/unloading stage 23. Then, the movable table 24 returns the carrier C to the station 102. Subsequently, the other carrier C placed at the station 103 is carried to the processing department 4, wafers W contained in the carrier C are processed and returned to the carrier C, and then the same carrier C is returned to the station 103.

In the cleaning apparatus 1 shown in Fig. 3, the loading/unloading stage 23 may be divided into a loading stage and an unloading stage. When the cleaning apparatus is provided with the loading stage and the unloading stage, a carrier is carried from the receiving stage 21 to the unloading stage, the is transferred from the unloading stage to the loading stage and is carried from the loading stage to the delivery stage 22.

Another embodiment of the moving table is hereby described

referring to Figs. 19-21. As shown in Fig. 19, a support 201 is provided at a rear end of the movable table 24 and a bracket 202 having a square bracket shape is fixed to an upper end of the support 201. The bracket 202 has a pair of forward extending portions 203, 204 whose lengths are different from each other. The extending portion 204 is longer than the extending portion 203. A light projector 205 and a light receiver 206 are provided at the front ends of the extending portions 203, 204 respectively and the light projector 205 and light receiver 206 form an orientation flat sensor.

The light projector 205 is capable of irradiating sensor light 20 toward the light receiver 206. The light projector 205 and the light receiver 206 are offset to each other by a length L in the direction from the front end to the rear end of the bracket 202.

As shown in Fig. 20, when the movable table 24 is horizontally moved below the stage 21, the scanning by the orientation flat sensor takes place simultaneously with that of the wafer counter 60. In Figs. 20 and 21, when the light projector 61 and the light receiver 62 of the wafer counter 60 are positioned at both sides of the lower end of the wafer W contained in the carrier C, the light projector 205 and the light receiver 206 of the orientation flat sensor are positioned at both sides of the upper end of the wafer W.

In Fig. 21, the wafer W is placed in a proper manner where an orientation flat  $W_p$  of the wafer W is positioned at the top of the wafer W. In this case, the sensor light 207 irradiated from the light projector 205 reaches the light receiver 206 without being cut off by the wafer W.

On the other hand, when the wafer W is placed in the carrier C in a manner where the wafer is rotated beyond a permitted angle (normally angles of  $\pm 5$  degrees) indicated by a two-dot chain line in Fig. 21, the sensor light 207 irradiated from the light projector 205 does not reach the light receiver 206 because the sensor light 207 is cut off by the wafer W.

Fig. 19 shows one of the plurality of wafers W contained in the carrier C (not shown in Fig. 19) placed on the stage 21 (not shown in Fig. 19). Since the light projector 205 and the light receiver 206 are offset to each other, the sensor light 207 crosses with an inclination of angle  $\alpha$  (normally about 5 degrees) on which

the wafer W in the carrier C is positioned. Thus, a detection error, which could occur in the case where angle  $\alpha$  is zero, can be prevented.

- This container handling system is applicable not only to a cleaning apparatus of a batch processing system but also to other apparatus that carries out a predetermined process, such as a wafer cleaning apparatus that cleans wafers one at a time or a coating apparatus that applies a predetermined liquid to wafers. The substrates are not limited to semiconductor wafers and may be substrates other than semiconductor substrates, such as LCD substrates.
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What is claimed is:

1. A substrate processing apparatus comprising:
  - a plurality of stages, on each of which a container for containing substrates therein is to be placed; and
  - a first section at which the substrates are taken out from the container and/or are put into the container, wherein a first stage amongst the stages is provided at the first section; and
  - a movable table carrying the container between the first stage and one of the stages other than the first stage, while the container being placed thereon.
2. The substrate processing apparatus according to claim 1, wherein each of the stages has a cut-away area extending from one end of the stage at least to a portion of the stage on which the container is to be placed, and wherein a portion of the cut-away area corresponding to the portion of the stage on which the container is to be placed has a shape that allows the movable table to move vertically through the portion of the cut-away area.
3. The substrate processing apparatus according to claim 2, further comprising:
  - a horizontal moving mechanism horizontally moving the movable table between a first position adjacent to the portion of the stage on which the container is to be placed and a second position apart from the stage; and
  - a lifting mechanism vertically moving the movable table.
4. The substrate processing apparatus according to claim 3, wherein the horizontal moving mechanism has a guide rail that guides the movable table for a horizontal movement thereof,
  - said apparatus further comprising a turning mechanism turning the guide rail in a horizontal plane between a first position where at least a portion of the guide rail is located below the portion of the stage on which the container is to be placed and a second position where the guide rail is withdrawn from a space below the stage.

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9. A substrate processing apparatus according to claim 8, further comprising a controller controlling operations of the first and the

second shutters so that the second shutter is closed when the first shutter is opened, and the first shutter is closed when the second shutter is opened.

10. The substrate processing apparatus according to claim 2, further comprising a sensing device provided at the movable table and inspecting a condition of the substrates contained in the container.

11. The substrate processing apparatus according to claim 10, wherein the sensing device includes a first sensor unit, wherein the first sensor unit is positioned higher than a mounting surface of the movable table so that the first sensor unit can go to a lower portion of the container through the cut-away area of the stage when the container is placed on the stage and the movable table is positioned lower than a mounting surface of the stage, and wherein the first sensor unit inspects the condition of the substrates contained in the container, when the movable table is horizontally moved below the stage while the container is kept on the stage.

12. The substrate processing apparatus according to claim 11, wherein the sensing device inspects, as the condition of the substrates contained in the container, the number of the substrates contained in the container and whether or not there is any jump slot in the carrier.

13. The substrate processing apparatus according to claim 10, wherein the sensing device includes a second sensor unit, wherein the second sensor unit is positioned higher than a mounting surface of the movable table so that the second sensor unit can be positioned in the vicinity of upper portions of the substrates contained in the container when the container is placed on the stage and the movable table is positioned lower than a mounting surface of the stage, and

wherein the second sensor unit inspects whether or not a

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positioning portion of each substrate is placed in a correct position, when the movable table is horizontally moved below the stage while the container is kept on the stage.

14. The substrate processing apparatus according to claim 1, further comprising:

a second section at which the container is received from an external of the apparatus, wherein a second stage amongst the stages is provided at the second section; and

a third section at which the container is delivered to the external of the apparatus therefrom, wherein a third stage amongst the stages is provided at the third section,

wherein the moving table transports the container between the first, second and third stages.

15. The substrate processing apparatus according to claim 1, further comprising a passage means through which the moving table moves and transports the container between the first stage and the another stage.

16. A method of carrying a container for containing substrates between two stages included in a substrate processing apparatus, said method comprising the steps of:

(a) moving a movable table for transporting a container to a position below a surface of a first stage on which a container is placed thereon;

(b) raising the movable table through a cut-away area formed in the first stage to a position above the surface of the first stage, thereby lifting up the container from the first stage by the movable table;

(c) withdrawing the movable table, on which the container is placed, from a position above the first stage;

(d) moving the movable table to a position above a second stage; and

(e) lowering the movable table through a cut-away area formed in the second stage to a position below a surface of the second stage, thereby placing the container on the second stage.

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positioning the movable table at a position outside the first stage and lower than a level on which the surface of the first stage lies;

said method further comprising the step of (f) inserting a sensing device, provided at the movable table into the container, thereby inspecting a condition of substrates contained in the container while the movable table is moving horizontally.

in step (f), the sensing device inspects, as the condition of the substrates contained in the container, the number of the substrates contained in the container and whether or not there is any jump slot in the carrier.

in step (f), the sensing device inspects, as the condition of the substrates contained in the container, the number of the substrates contained in the container and whether or not a positioning portion of each substrate is placed in a correct position.

(a) delivering a plurality of containers containing substrates onto a receiving stage;

(c) taking out substrates from the container transferred to the unloading stage; and

21. A method of handling containers for containing substrates,



(d) delivering the plurality of containers collected on the delivery stage after the completion of the step (c).

(g) delivering the plurality of containers collected on the delivery stage after the completion of the step (f).

23. The method according to claim 16, further comprising the step of processing the substrates taken out from the container in step (c), wherein the substrates putted into the container in the step (d) have been processed.

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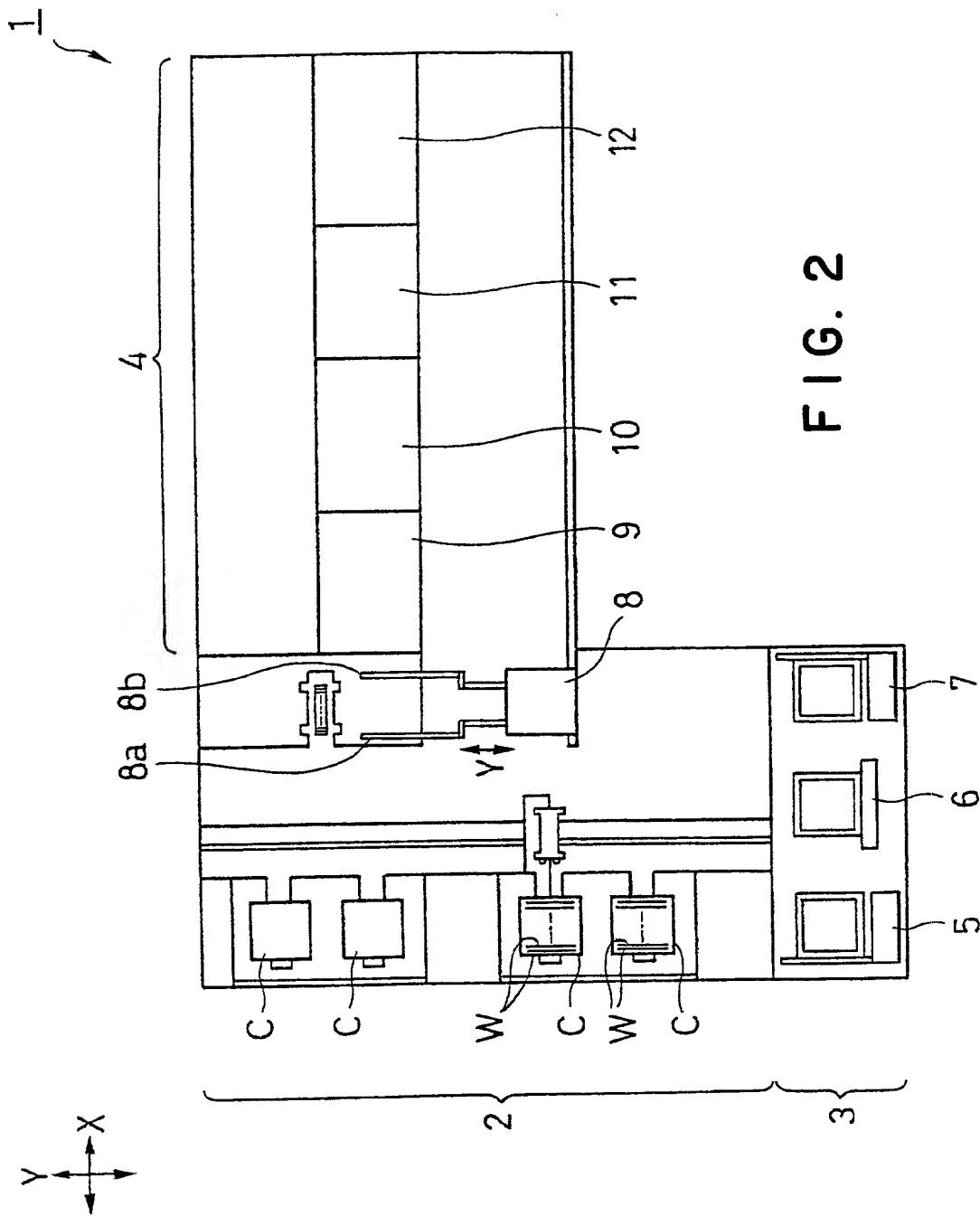


FIG. 2

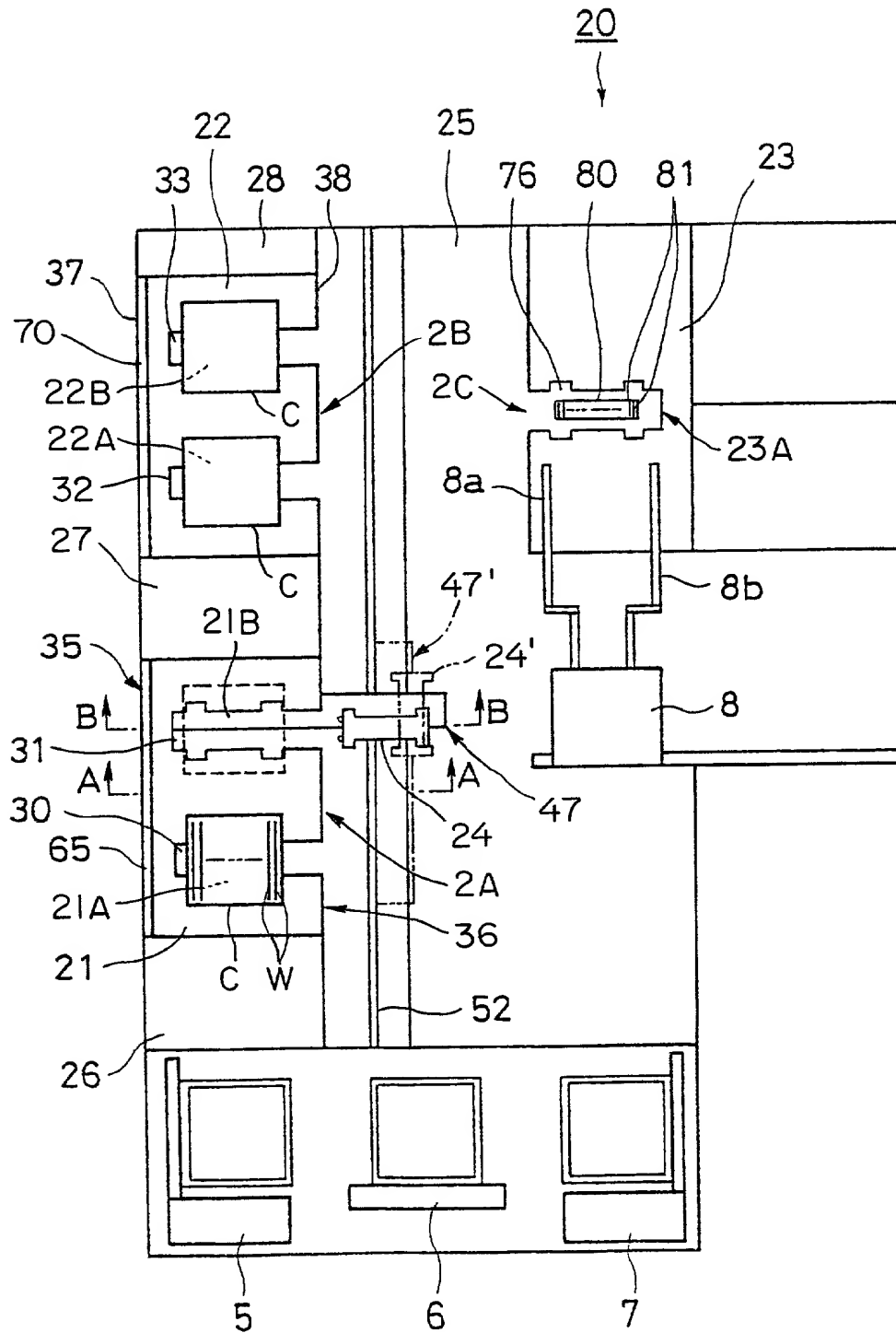


FIG. 3

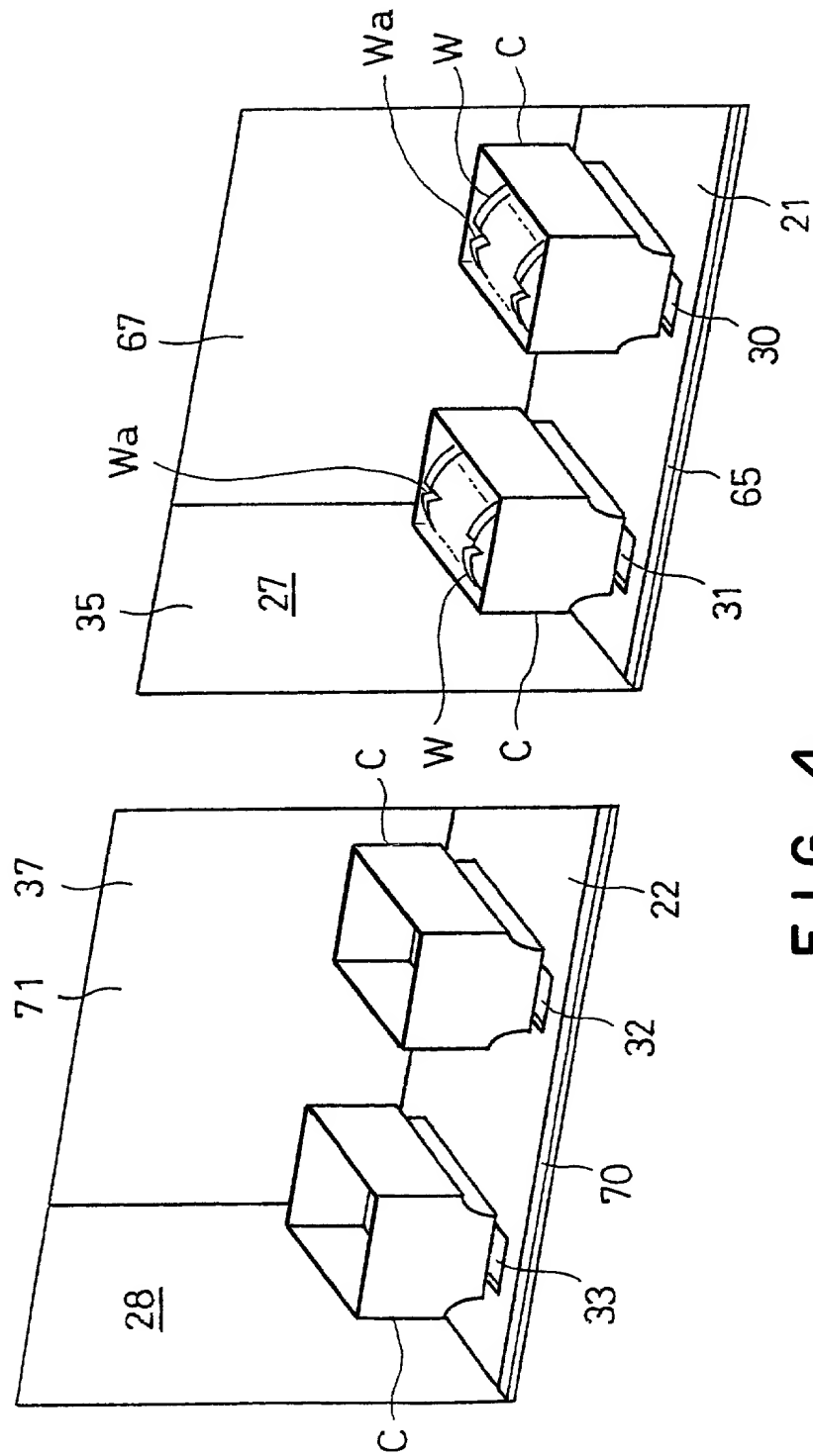
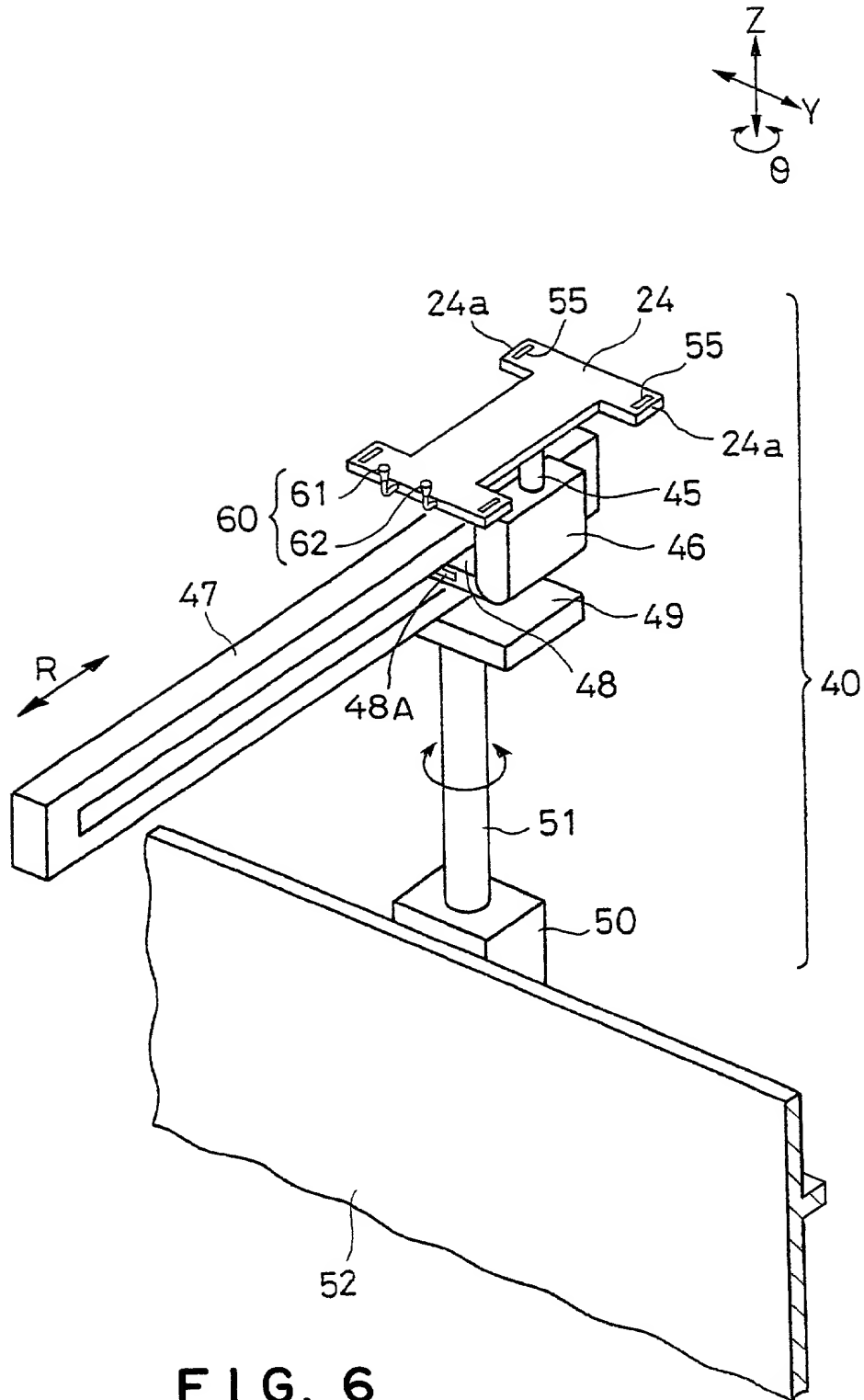


FIG. 4







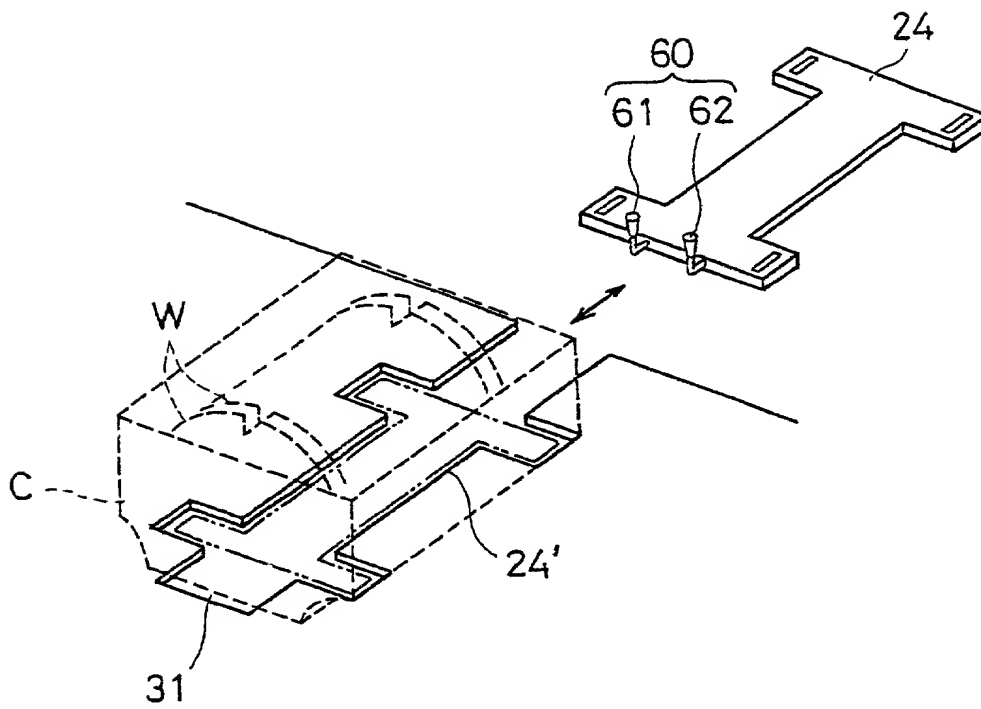


FIG. 7

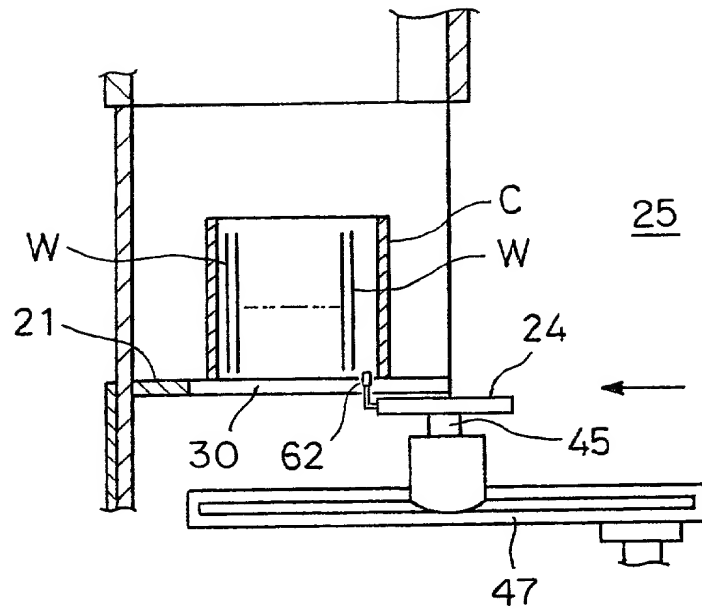


FIG. 8

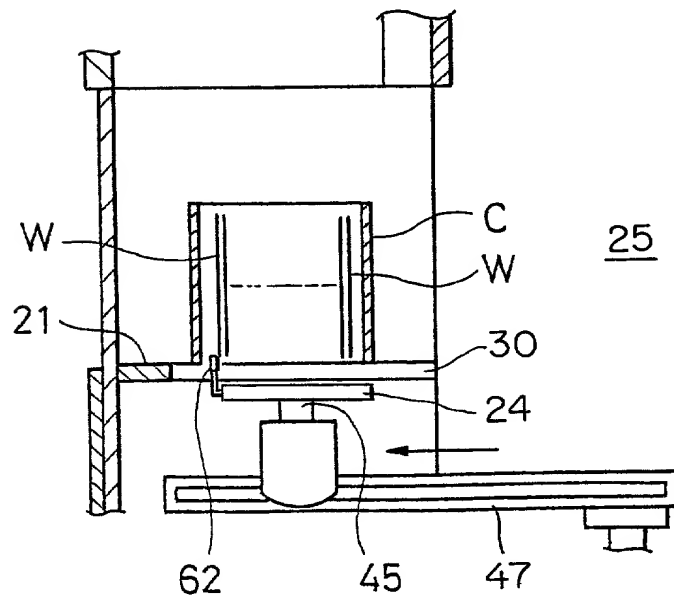
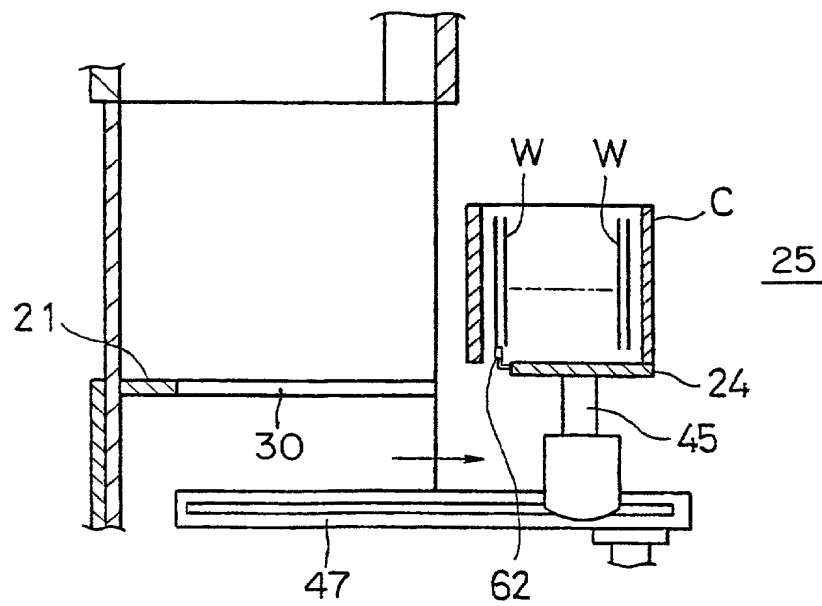
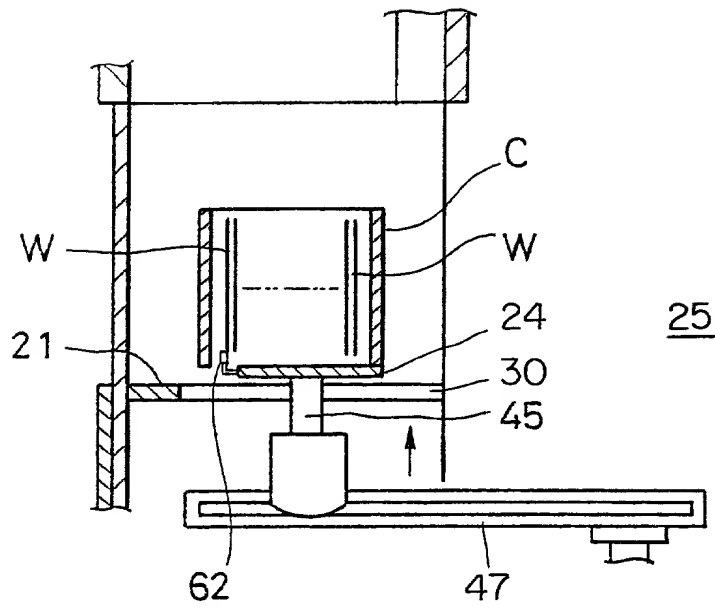


FIG. 9

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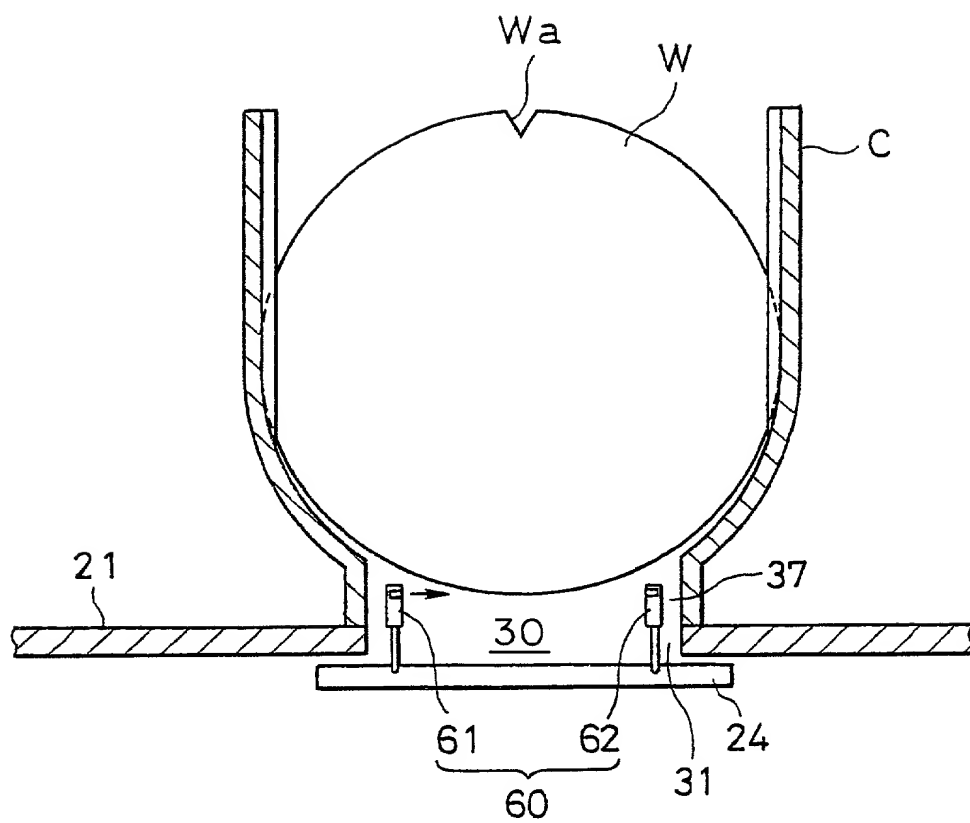


FIG. 12

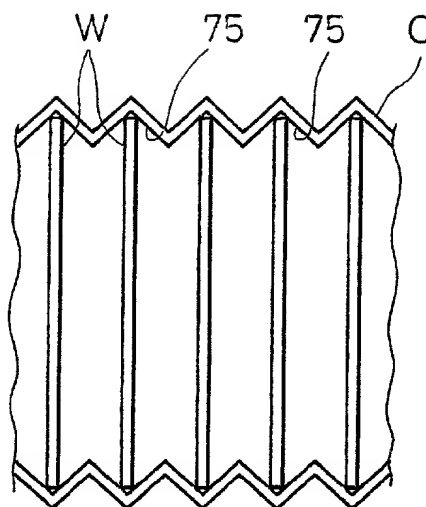


FIG. 13A

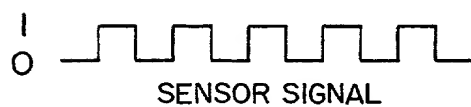


FIG. 13B

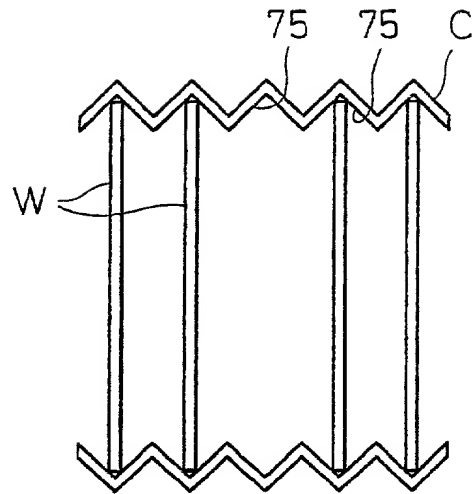


FIG. 14A



FIG. 14B









FIG. 17

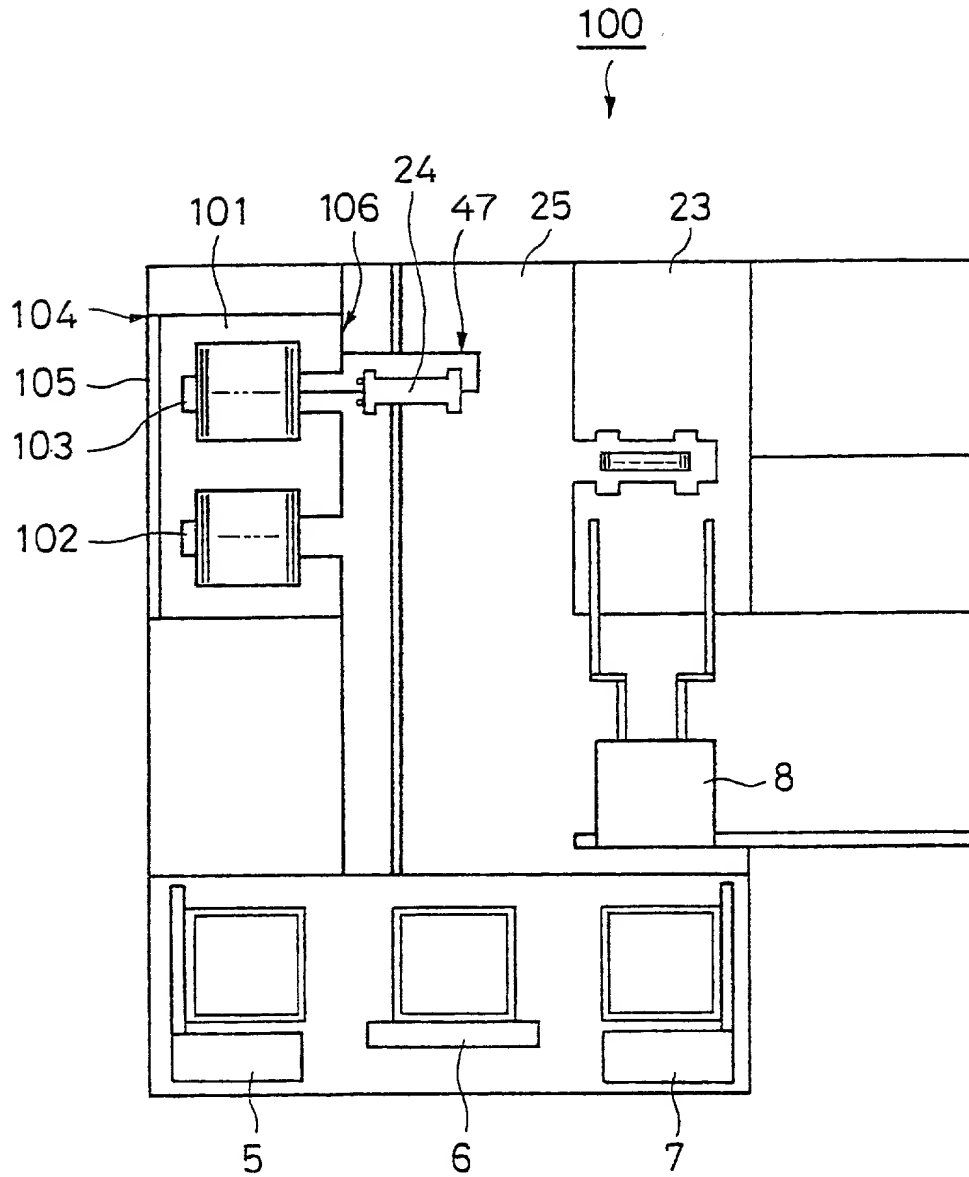


FIG. 18



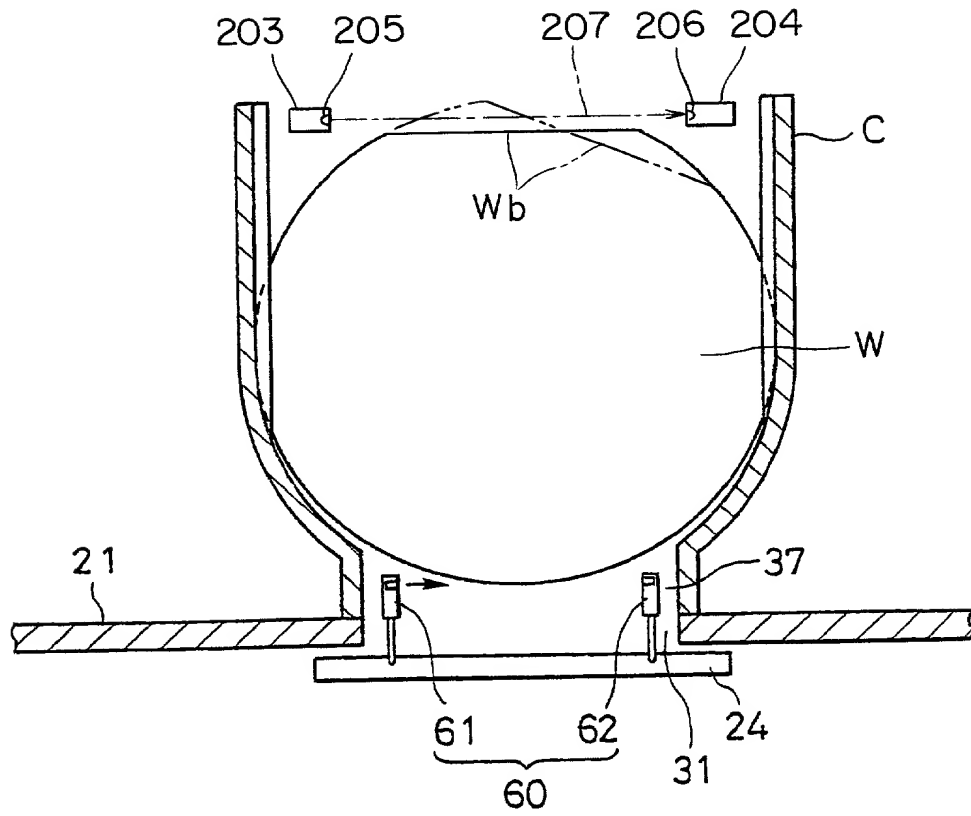


FIG. 21